

1 Land 'moving map' fields

- **Norm. Acc:** Normal acceleration (perpendicular to movement, in circular movements).
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- **AGL:** Altitude from Ground Level.
- **L. Alt.:** Altitude of the land we are overflying.
- **Alt:** Altitude over sea level.
- **Maximum height::** In current flight.
- **Battery:** Remaining energy in PC/PDA.
- **Demora:** Diferencia, en grados, entre el rumbo programado (al siguiente waypoint) y el rumbo que realmente estamos siguiendo.
- **Differential:** GPS gives differential signal (submetric accuracy).
- **Dist. Dest.:** Distance to destination (last waypoint of the route).
- **Dist. to next:** Distance to next waypoint.
- **HDOP:** Horizontal Dilution Of Precision (estimated current accuracy of the GPS).
- **Free memory:** Free space in PDA's memory.
- **Goto Arrow:** An arrow will point to next waypoint.
- **Hour Dest:** Estimated hour to reach destination (last waypoint of the route) (at current speed).
- **Hour Next:** Estimated hour to reach next waypoint (at current speed).
- **Number of points:** Track points saved up to this moment.
- **Partial Odom.:** Covered distance from current flight start (reset keeping the pencil pressed on the field).
- **Total Odom.:** Aggregate distance of all your flights (it can be reset).
- **Slope:** Slope of our current movement.
- **Pgps:** Position from GPS.
- **Rad.T:** Radius of turn.
- **Brg. next:** Bearing to next waypoint.
- **BRN:** Orientation of our course in horizontal plane (0 = N, 90 =E, 180 = S, 270 = W)

- **Place:** When a vector map is loaded with information about the zone, this will show the name of the element which fits with our current position.
- **E.T. Dest:** Estimated time to reach destination (last waypoint of the route) (at current speed).
- **E.T. Next:** Estimated time to reach next waypoint (at current speed).
- **Temper.:** Temperature.
- **Max. sp.:** Maximum speed in current flight.
- **V:** Current speed.
- **Mean speed:** Mean speed from start to now.
- **Vert. S:** Vertical speed.
- **Next WPT:** Name of the waypoint you are going to.